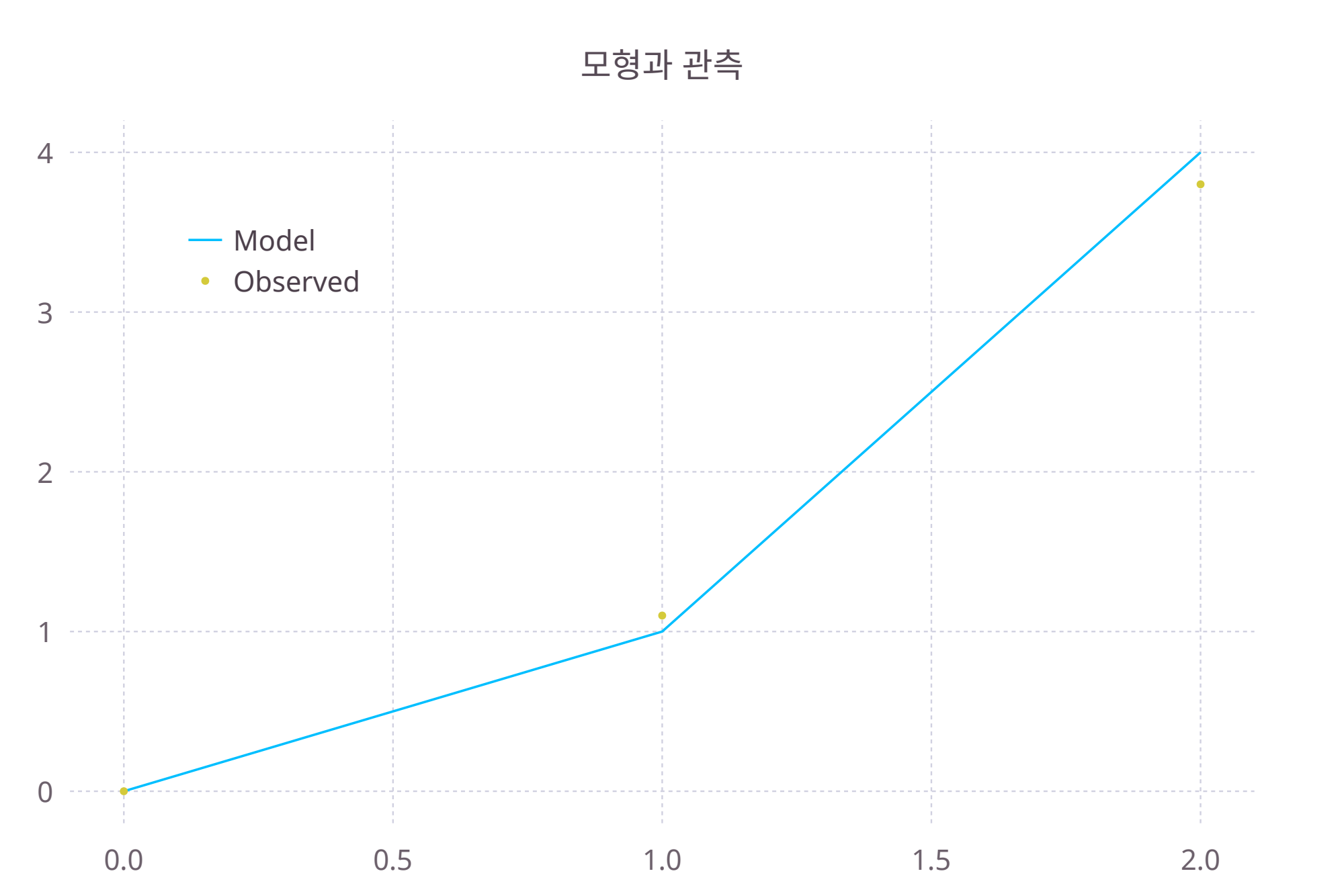

모형과 관측
Model
Observed
4
3
2
1
0
0.0
0.5
1.0
1.5
2.0